

A Hybrid Method for Magnetic Resonance Brain Images Classification and Segmentation Using Soft Computing Techniques

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Abstract: Nowadays, brain tumor is a serious life-threatening disease that can often be treated with risky surgeries. Various classification and segmentation methods for MR (magnetic resonance) brain images have been proposed, but the expected accuracy value could not be reached so far. In this paper, we proposed a hybrid approach that includes modified fuzzy C-means and artificial neural network (ANN) classifier. It consists of five stages: (a) noise removal, (b) feature extraction, (c) feature selection, (d) classification, and (e) segmentation. Initially, a genetic optimized median filter is used to remove noise present in the input image, and then the essential features are extracted and selected using discrete wavelet transform and principle component analysis algorithms, respectively. The normal and abnormal images are classified using the ANN classifier. Finally, it is processed through a modified fuzzy C-means algorithm to segment the tumor portion separately. The proposed segmentation technique has been tested on the BRATS dataset and produces a sensitivity of 98%, Jaccard index of 97%, specificity of 98%, and accuracy of 95%.

Keywords: ANN; brain tumor; DWT; genetic optimized median filter; modified fuzzy C-means; PCA

I. INTRODUCTION

The brain is a vital organ in the human body, and every action of the human body is controlled by the brain. Brain tumor is one of the most dangerous cancers that cause death. It is an unwanted growth of abnormal cells in the brain and is classified as primary and secondary brain tumors [\[1](#page-6-0)]. Primary brain tumor cells originate in the brain, whereas secondary brain tumors cells grow in other parts of the body [\[2](#page-6-0)]. Benign and malignant tumors belong to primary brain tumors. Malignant tumor is more dangerous compared to benign, and it can easily be predicted as its intensity levels are different from the neighboring cells [\[3](#page-7-0)–[5\]](#page-7-0).

Generally, brain tumors can be detected using various scanning techniques such as computed tomography (CT) and magnetic resonance imaging (MRI). MRI scanning results in high-quality images, especially hard tissues are clearly visible [\[6](#page-7-0)]. Accurate identification and delineation of tumor regions provide crucial information to healthcare professionals, enabling them to make informed decisions regarding patient management. In recent years, advancements in imaging technologies and computational techniques have propelled the development of sophisticated algorithms for brain tumor segmentation. These techniques have demonstrated remarkable potential in improving the accuracy, efficiency, and reliability of tumor delineation. The important advancements for locating brain tumors are feature extraction and determination.

There are numerous features, including GLCM, statistics, wavelet features, texture, and region-based characteristics. Additionally, there are many ways to extract the necessary information from the image. Utilizing a vast array of features for classification is particularly effective deterrent. Therefore, it is necessary to select the important qualities. It involves lowering the computational complexity while also improving classification accuracy. For choosing features from the image, a variety of deep learning and optimization algorithms have been used, including Fisher linear discriminant analysis, K-nearest neighbor, decision tree, multilayer perceptron, and support vector machine (SVM). A powerful strategy for the multicategory classification problem was discovered in artificial neural network (ANN) classification methods. Many researchers, clinicians, and scientists have proposed different brain tumor detection and segmentation techniques, but the predicted accuracy is not reached so far. Hence, we propose a fully automated hybrid technique that includes modified fuzzy C-means and ANN classifier.

Due to its ease of use, the fuzzy C-means (FCM) algorithm is one of the most well-liked segmentation techniques that has been extensively employed in medical research. The debut of FCM is what led to its success. When pixels in a cluster are weighted according to how closely they resemble each other, fuzziness is present. FCM neglects the spatial information surrounding each pixel, which makes it sensitive to noise, which is a significant drawback of standard FCM clustering. The FCM algorithm cannot manage the various levels of noise that are found in medical images. The creation of noise-free pictures via hardware innovations remains a difficulty despite all the advancements made in MR imaging. There are two ways to fix this problem with FCM: (1) create FCM extensions that are more noise resistant and

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(2) enhance image denoizing techniques. Prior research has suggested a number of extensions for the first method to enhance FCM performance. These extensions may be distinguished by their predominant application of modifications to the spatial domain, transform domain, and metaheuristics. Due to their dependence on the original noisy image, these approaches are still susceptible to high levels of noise even though the proposed improvements improve FCM segmentation of noisy MR images. In the second approach, noise from the original MR images is removed before segmentation using a well-liked technique known as denoizing.

In recent times, ANNs have emerged as a promising solution, offering significant improvements over previous techniques. Traditional techniques for brain tumor segmentation often relied on handcrafted features and rule-based algorithms. These methods involved manual selection of features, followed by the application of thresholding, region growing, or morphological operations to delineate tumor regions. Although these techniques were useful to some extent, they often struggled with handling tumor heterogeneity, intensity variations, and irregular tumor shapes. The accuracy and reliability of these approaches were limited, and they heavily relied on expert knowledge and manual interventions. The rise of ANNs has revolutionized the field of medical image analysis, including brain tumor segmentation. ANNs offer powerful computational models capable of learning complex patterns and relationships directly from the data. By leveraging their ability to automatically extract high-level features, ANNs can effectively handle the challenges posed by brain tumor segmentation. These networks can capture intricate spatial information, learn from diverse examples, and generalize well to unseen data. ANNs provide several advantages over previous techniques in the context of brain tumor segmentation. First, ANNs can learn discriminative features directly from the raw input data, eliminating the need for manual feature engineering. This ability enables the networks to capture subtle patterns and variations in tumor regions, improving the accuracy of segmentation. Second, ANNs can handle the inherent heterogeneity of brain tumors by learning and modeling complex relationships between different tumor components and surrounding tissues. This capability allows for more precise delineation of tumor boundaries, including the tumor core, edema, and necrotic regions. Additionally, ANNs have the potential to adapt and generalize well to diverse imaging modalities, making them versatile tools in multimodal brain tumor segmentation. When compared to previous techniques, ANNs have demonstrated superior performance in various studies and competitions focused on brain tumor segmentation. The learned representations and internal feature representations of ANNs enable them to capture both local and global context, enhancing segmentation accuracy. Additionally, ANNs have shown robustness to noise, intensity variations, and imaging artifacts, making them more reliable in real-world clinical scenarios. Moreover, ANNs can leverage transfer learning, where pretrained models on large datasets can be fine-tuned for specific segmentation tasks, reducing the need for large annotated datasets.

The rest of the paper is organized as follows: Section II discusses the related works. Section [III](#page-2-0) presents the proposed methodology. Section [IV](#page-4-0) outlines the results and discussions, and the conclusion and future scope are discussed in Section [V.](#page-4-0)

II. LITERATURE SURVEY

During the transmission and acquisition of MRI images, unwanted signals can interrupt and contaminate the quality of the images and therefore extraction of vital features from the image becomes difficult. V.V.S. Sasank et al. [[7\]](#page-7-0) proposed a hybrid technique that combined the lattice Boltzmann method and modified sunflower optimization algorithms for brain tumor segmentation and achieved an accuracy of 95.23%. P. Supraja et al. [\[8](#page-7-0)] developed an efficient deep learning technique combined with a fuzzy K-means algorithm to segment the tumor region separately, and it is verified on the BRATS dataset and produces an accuracy of 94%. Marwan A.A. Hamid et al. [\[9](#page-7-0)] used spatial filters to remove undesired information and noises further supporting vector machine is used to classify the MRI brain tumors and obtained an accuracy of 95%. Jose Bernal et al. [\[10](#page-7-0)] discussed different deep convolutional neural networks (CNNs) in their review article. El-Sayed Ahmed et al. [\[11](#page-7-0)] used hybrid intelligent techniques. They used DWT and PCA (principal component analysis) to extract and select the features of MRI images, respectively, and feed-forward backpropagation ANN and K-nearest neighbor to classify the normal and abnormal MRI brain images. Ming-Chuan Hung et al. [[12\]](#page-7-0) proposed a novel and efficient algorithm known as the psFCM algorithm, which reduced the computation time required to partition a dataset into desired clusters. Keh-Shih Chuang et al. [[13\]](#page-7-0) presented a fuzzy c-means algorithm that incorporates spatial information into the membership function for clustering. S. Deepak et al. [[14\]](#page-7-0) adopted a technique that combines CNN features with SVM for classification of the medical images, and it is verified on figshare dataset and attained overall classification accuracy of 95.82%. Abbasi et al. [\[15](#page-7-0)] presented another fully automated tumor detection methods that use different clustering algorithms to segment the brain MRI into different regions. The partitioned regions become the ROI for further analysis. In order to diagnose esophageal cancer, Xue *et al.* [\[16](#page-7-0)] used the concept of merging CNN and SVM to solve their microvascular morphological classification challenge. Despite having more training data, the CNN-SVM combination outperformed the stand-alone CNN classifier in terms of accuracy.

The segmentation of uterine fibroids in MR-guided focused ultrasound surgery and the segmentation of metastatic brain cancer in neuro-radio surgery are two clinical cases involving bimodal MR image analysis. Rundo et al. [\[17](#page-7-0)] presented a scalable system for medical image preprocessing, automatic global thresholding, and segmentation. Fast curvelet transform was used by Nayak et al. [\[18](#page-7-0)] to extract patient features from binary and multiclass brain MR datasets, and kernel extreme learning machine was used to classify the features. Cui et al. [\[19](#page-7-0)] developed an autonomous segmentation model utilizing a cascaded deep learning CNN. It consists of two different kinds of networks: an intra-tumor classification network (ITCN) and a tumor localization network (TLN). The tumor region can be separated from the MRI images using TLN, and it can be divided into more manageable portions using ITCN. A model for tumor segmentation and classification was created by Chinmayi et al. [\[20](#page-7-0)] utilizing the Bhattacharya coefficient.

The undesired MRI sections, such as the skull, are removed using an anisotropic filter. It trains the MRI image of the brain cancer using deep learning CNN. Additionally, it uses a quickbounding box method to isolate the cancer area. A dense FCNN with a dense conditional field was used by Shaikh *et al.* [\[21](#page-7-0)] in 2018 to segment brain tumors for the Multimodal Brain Tumor Image Segmentation (BraTS 2017) challenge. Dense conditional fields were implemented as a postprocessing step to fully utilize context information, and dense blocks were used to facilitate information flow. A deep supervised 3D squeeze-excitation (SE) V-Net was proposed by Liu *et al.* [\[22](#page-7-0)] The average dice for the WT,

TC, and ET on BraTS 2017 reached 89.3%, 80%, and 74.7%, respectively. 3D SE blocks were introduced to drive the V-Net to concentrate on the relevant feature channels.

III. PROPOSED METHODOLOGY

The feature extraction phase plays a vital role in the medical imaging field. The output of feature extraction methods depends on the output of preprocessing methods. We present a framework to filter, segment, extract the desired features, and finally use a classifier to distinguish between types of brain tumors. In this study, the performance of the proposed method has been verified on the BraTS 2015 and BraTS 2017 datasets.

The proposed framework consists of five stages: (i) preprocessing, (ii) feature extraction with DWT, (iii) feature selection using PCA, (iv) classification of images using ANN, and (v) segmentation using modified fuzzy c-means, and these stages are shown in Fig. 1.

A. PREPROCESSING

The proposed method uses a hybrid technique to extract tumors in MR images. MRI is a simple and low-risk technique that provides detailed tissue images of the brain. Though we get good-quality images using MRI, however, the skull and scalp are the unwanted components that may contain noise.

The process of removing artifacts and noise present in the MR images is known as preprocessing. Based on the nature of noise various filters such as Wiener filter, Gaussian filter, and Mean filter are used. In this proposed technique, genetic optimized median filter (GOMF) is used to remove noise and artifacts present in the brain MRI image. At each location, GOMF selects a vector randomly, and partitions that vector into 'N' segments. On each segment, this filtering operation is applied and thus this algorithm gives the optimum weighting factor for each segment. This filtering operation is applied repeatedly on the given image to get the expected image quality. The evaluation function is

$$
E = (U - V.WT)2
$$
 (1)

where "E" represents total square error. "U" indicates uncorrupted pixel value. "V," and "W" denotes filtered output and weighting vector, respectively.

B. FEATURE EXTRACTION WITH DWT

To extract features from the above preprocessed images, we used discrete wavelet transform (DWT). Though there are many

Fig. 2. Three-level Haar wavelet decomposition tree.

mathematical transformation techniques present in the frequency domains such as Fourier transform and Laplace transform, we deal with wavelet transform that is generally used for image analysis and data compression. DWT is a powerful technique that uses dyadic scales and positions. In this work, DWT extracts features from the denoized image. Unlike Fourier transform, DWT offers knowledge about time and frequency domains.

Let us assume that $x(t)$ is a square-integrable function, and that the continuous wavelet transform of $x(t)$ relative to a given wavelet $\varphi(t)$ is defined in equation (2)

$$
W_{\varphi}^{(g,\mathrm{h})} = \int_{-\infty}^{\infty} x(t)\varphi_{g,\mathrm{h}}(t)dt
$$
 (2)

where
$$
\varphi_{g,h}(t) = \frac{1}{\sqrt{g}} \varphi \left(\frac{t - g}{h} \right)
$$
 (3)

In the third equation, g and h are dilation and translation parameters, respectively. $\varphi_{\text{gh}}(t)$ can be determined from the mother wavelet $\varphi(t)$ by translation and dilation.

In the wavelet analysis, different kinds of wavelets gained popularity, out of which Haar wavelet is the simplest wavelet often used in most of the applications. In this work, Haar wavelet transform is used for decomposing the given image to extract the features. Figure 2 represents the 3-level decomposition tree.

Here is the given image, having 1, 2, 3 represents approximated and detailed coefficients at levels 1, 2, and 3. As the number of decomposition levels increases, we get a compactor but coarser approx. information.

Fig. 1. Block diagram of the proposed framework.

C. FEATURE SELECTION USING PCA

The excessive features that are extracted using DWT consume more computation time and storage memory. Principle component analysis (PCA) is a statistical approach to select the principal features of a dataset based on their total variance. Thus, PCA reduces the dimension of the dataset through the following steps:

- a. Image normalization
- b. Determine the covariance matrix
- c. Calculate Eigen vectors and its values from the covariance matrix
- d. Transform image data into the new basis

Before performing PCA, it should be noted that the input image should be normalized to get a unit variance and zero mean. To calculate Co-variance matrix, we need to find the mean of the image using equation 4.

$$
T_m = \frac{1}{K} \sum_{M=1}^{K} X_i
$$
 (4)

The covariance matrix (B) is calculated as

$$
B = X_i - T_m \tag{5}
$$

Finally, the Eigen vectors are calculated from equation 6.

$$
E = BB^T \tag{6}
$$

The Eigen vectors with higher values are selected, and these are the principal features of the given dataset.

D. ANN CLASSIFICATION

ANN is a biologically inspired concept, and it is the subfield of artificial intelligence. As neurons are interconnected to each other in the human brain, similarly ANN consists of neurons linked to each other called as nodes. The three layers of ANN are the input layer, hidden layer(s), and output layer. The input layer is multiplied with input hidden weights.

$$
H_j = x_j + \sum_{k=1}^{n} U_k W_{ij}^h
$$
 (7)

$$
O_j = x_i + \sum_{j=1}^{b} W_{ij}^o f(H_j)
$$
 (8)

$$
E = \frac{1}{2n} \sum_{i=0}^{h-1} \sqrt{(T_i - Y_i)^2}
$$
 (9)

where H_i is the hidden function, x_i is the input bias value, O_i is the output function, x_i is the output bias value, and E is the mean square error (MSE). During testing, the minimum MSE-weighted values are given to the ANN for classification. Based on the obtained value, test image is classified into normal or abnormal image.

 Y_i = normal image for $0 \le T_i < 0.75$

$$
Y_i
$$
 = abnormal image for 0.75 $\leq T_i$

where Y_i and T_i are the output and target values, respectively.

E. MODIFIED FUZZY C-MEANS

The ANN-classified abnormal images are given to the modified fuzzy C-means algorithm. Let us discuss clusters, their types, fuzzy C-means, and finally modified fuzzy C-means algorithm. Unlabeled patterns are partitioned or grouped into clusters such that similar patterns form a cluster. Hard clustering or crisp clustering and fuzzy clustering are the two approaches widely used in clustering. In crisp clustering, boundaries between adjacent clusters must be well-defined. But in practical cases, boundaries between adjacent clusters cannot be defined clearly. For such cases, fuzzy clustering is a more suitable method to classify these unlabeled patterns.

Among all fuzzy clustering techniques, fuzzy C-means (FCM) technique is widely used. Let $A = \{a1, a2, \ldots, aM\}$ denotes an image with " M " pixels and that is to be partitioned into " C " clusters, where a_i indicates multispectral data.

The FCM algorithm is an iterative optimization algorithm which minimizes the under defined cost function.

$$
J = \sum_{j=1}^{M} \sum_{i=1}^{c} u_{ij}^{m} ||a_j - v_i||^2
$$
 (10)

where u_{ij} indicates the membership of x_j pixel in the i^{th} cluster, and v_i is the ith cluster center as shown in equations 11 and 12, respectively. ' m ' is the degree of fuzziness. In this study, we used $m = 2$.

The minimization of the above cost function depends on the membership value that is given to the pixels. That means the pixels nearer to the centroid of their cluster should be given high membership values and the lower membership values to the far pixels from the centroid.

$$
u_{ij} = \frac{1}{\sum_{k=1}^{c} \left(\frac{||a_j - v_i||}{||a_j - v_k||} \right)^{\frac{2}{(m-1)}}}
$$
(11)

And

$$
v_i = \frac{\sum_{j=1}^{M} u_{ij}^m a_j}{\sum_{j=1}^{M} u_{ij}^m}
$$
(12)

By appropriate guess for every cluster center, FCM converges to a solution for v_i representing local minima of the cost function. The membership function discussed in equations 11 and 12 should be modified to get the accurate spatial information of the pixels. Thus, we present modified fuzzy C-means algorithm.

The modified membership function is defined as

$$
u'_{ij} = \frac{u_{ij}^m s_{ij}^y}{\sum_{k=1}^n u_{kj}^m s_{kj}^y}
$$
 (13)

$$
S_{ij} = \sum_{k \in N(a_j)} u_{ik} \tag{14}
$$

 S_{ii} is the function in spatial domain, which enhances the membership value of the pixel, and it presents the probability of pixel a_i that belongs to the *i*th cluster. $N(a_j)$ is square window centered on pixel a. in the spatial domain $m \times$ are window parameters a_i in the spatial domain. m , y are window parameters.

We know that $A = \{a1, a2, \dots a_M\}$ denotes an image with "*M*" pixels and let $v = \{v1, v2, \dots v_c\}$ be the set of centers.

The algorithm for Modified FCM is

- 1. Set the number of clusters "C" and window parameters m , y .
- 2. Calculate $U^b = [U_{ij}^{\prime b}]$ using equation [11](#page-3-0)
- 2. Calculate $U = [U_{ij}]$ using equation [12](#page-3-0)
- 4. Repeat the above steps, until $|U^b U^{(b-1)}| < \epsilon$ where ϵ is termination ϵ belongs to [0, 1] b is the no of iteration \in is termination, \in *belongs to* [0,1], *b* is the no. of iteration steps steps.

Thus, it is observed that 14 iterations are performed. During 14th iteration, the above conditions are satisfied. Hence, the iteration process is stopped.

IV. RESULTS AND DISCUSSIONS

In this paper, the input MRI brain images are taken from the BRaTS 2015 and BRaTS 2017 datasets. The proposed method is simulated using MATLAB R 2016 developed by Math works Inc. In this proposed framework, benign tumors (training-140, testing-115) and malignant tumors (training-140, testing-115) are used for implementation. The simulation results of the proposed work are shown in Fig. 3.

A. PERFORMANCE ANALYSIS OF GOMF

For preprocessing, GOMF is used, and its results are shown in Table I. The GOMF performance is evaluated by calculating the following metrics.

(i) PSNR and MSE: PSNR stands for peak signal to noise ratio. It represents a measure of the peak error.

$$
PSNR(f,g) = 10\log_{10}(255^2/\sqrt{\text{MSE}(f,g)})\tag{15}
$$

$$
MSE(f,g) = (1/MN) \sum_{j=1}^{M} \sum_{j=1}^{N} (f(i,j) - g(i,j))^2
$$
 (16)

where $f(i,j)$, $g(i,j)$ are the original and modified images, respectively, (i,j) is the pixel position of $M \times N$ image, and MSE is the mean square error.

(ii) SSIM: SSIM means structure similarity index metric. The name itself indicates that it measures similarity between the reference image and the original image. By multiplying the three similar aspects such as luminance, contrast, and structure, we can calculate the SSIM.

Fig. 3. Simulation results of proposed technique: (a) preprocessed image, (b) image sharpening, (c) feature selection using PCA, (d) fuzzy clustered image, (e) at 14th iteration, and (f) final segmented image.

$$
SSIM(f,g) = [(2\mu f \mu g + c1)(2\sigma f g + c2)]/[(\mu f2 + \mu g2 + c1)(\sigma f2 + \sigma g2 + c2)] \tag{17}
$$

where μ_f , μ_g are mean values of f, g. c1, c2 are stabilizing constants and σ_f , σ_g are standard deviations of f, g, respectively.

(iii) Correlation: Correlation is mainly used to match the template image with the given image. If each pixel in an image has nonlinear relationship with its neighboring pixels, then such a relationship is defined as correlation.

Correlation =
$$
\sum_{i=1}^{M} \sum_{j=1}^{N} [(i * j * f(i,j) / R) - \mu_x * \mu_y] / (\sigma_x * \sigma_y)
$$
 (18)

(iv) MAE: MAE stands for mean absolute error

$$
\text{MAE} = (1/MN) \sum_{i=1}^{M} \sum_{j=1}^{N} (f(i,j) - g(i,j)) \tag{19}
$$

B. PERFORMANCE ANALYSIS OF FEATURE SELECTOR (PCA)

Though the features of input brain image are extracted using DWT, the required and essential features (feature subset) are selected by PCA method. The assessment metrics such as sensitivity, specificity, and accuracy are computed for feature subset and shown in Table II.

(i) Sensitivity: The sensitivity is defined as the quantity of actual positives, which are accurately predictable.

Sensitivity =
$$
\frac{BA}{BA + BI} \times 100\%
$$
 (20)

Table II. Performance comparison of feature subset parameters

Feature subset	Sensitivity (%)	Specificity (%)	Accuracy (%)
Intensity	82	72	93.78
Texture	86	81	92.86
Shape	83	70	94.86
Intensity + Texture	90	94	96.23
$Intensity + Shape$	92	91	97.46
$Shape + Texture$	94	95	97.62

Table III. Performance analysis of the ANN classifier

(ii) Specificity: The specificity is defined as the quantity of actual negatives, which are accurately predictable.

$$
\text{Specificity} = \frac{MA}{MA + MI} \times 100\% \tag{21}
$$

(iii) Accuracy: Accuracy gives the perfectness of the proposed method.

$$
Accuracy = \frac{BA + MA}{BA + MI + BI + MA} * 100\% \tag{22}
$$

where

BA (True Positive) : Benign tumor is accurately identified as benign tumor

BI (False Negative) : Benign tumor is inaccurately identified as malignant tumor

MA (True Negative) : Malignant tumor is accurately identified as malignant tumor

BA (False positive) : Malignant tumor is inaccurately identified as benign tumor

C. PERFORMANCE ANALYSIS OF ANN CLASSIFIER

After selecting the required features of brain MR image, the tumor classification is done using ANN classifier, and it classifies the tumor as either benign or malignant. The performance of the classifier is shown in Table III.

The ANN classifier classification accuracy is 96.52% for benign tumors and 98.26% for malignant tumors. Finally, the average accuracy of the ANN classifier is 97.3%, which is far better compared to earlier conventional classification methods.

D. PERFORMANCE ANALYSIS OF MODIFIED FUZZY-C-MEANS SEGMENTATION

The efficiency of the proposed technique, i.e., the modified fuzzyc-means segmentation method, is evaluated using the structural similarity index metric (SSIM). After extraction of the tumor portion, its area is computed and compared with ground truth images, and these values are presented in Table [IV](#page-6-0). As the name indicates, SSIM is used to find the similarity between segmented images and ground truth images.

After a thorough analysis of the results, we conclude that the proposed method is not affected by oversegmentation and produced an average SSIM value of 98.5%.

The proposed method is compared with the existing methods such as computational neural networks (CNN), fuzzy-k-means,

Sample No	Predicted tumor region	Extracted tumor region	Under segmentation	Over segmentation	SSIM
1	24.40	24.36	0.04	Ω	0.9832
$\overline{2}$	19.62	19.60	0.02	Ω	0.9769
3	25.21	25.11	0.10	$\mathbf{0}$	0.9652
$\overline{4}$	23.21	22.92	0.29	$\overline{0}$	0.9732
5	18.56	18.88	θ	0.32	0.9914
6	19.75	19.51	0.24	Ω	0.9876
7	15.52	15.23	0.29	$\overline{0}$	0.9752
8	14.76	14.43	0.33	Ω	0.9834
9	20.61	21.10	Ω	0.49	0.9926
10	23.65	23.60	0.05	Ω	0.9912
11	19.86	19.75	0.11	Ω	0.9836
12	20.58	20.47	0.11	Ω	0.9677
13	21.43	21.20	0.23	Ω	0.9736
14	24.12	23.97	0.15	Ω	0.9811
15	25.16	25.02	0.14	$\mathbf{0}$	0.9923

Table IV. Structural similarity index metric for various MR images

Table V. Performance analysis of proposed segmentation method with existing methods

Segmentation Technique	Sensitivity	Specificity	Jaccard index	Accuracy
CNN	83	86	83	85
Fuzzy-K-means	90	91	93	92
SS2DCN	86	94	82	90
KNN	82	92	81	87
Proposed method	98	98	97	95

skull stripping 2-dimensional convolutional networks (SS-2D-CN), and K-nearest neighbor. The performance of these techniques has been evaluated using various evaluation parameters and tabulated in Table V.

From the above analysis, we conclude that our proposed technique gives 98% sensitivity, 98% specificity, 97% Jaccard index, and a high accuracy of 95% compared to the existing methods as shown in (Fig. 4).

Fig. 4. Comparison of the proposed technique with the existing techniques.

V. CONCLUSIONS

In this paper, we proposed a hybrid technique for the classification and extraction of tumors from MR brain images. Initially, the images were obtained from BraTS 2015 and BraTS 2017 datasets. The MRI brain image was preprocessed using GOMF, and the features are extracted and selected using DWT and PCA algorithms, respectively. Then ANN classifier classified the images into normal and abnormal images. Finally, the modified fuzzy-c-means algorithm was used to segment the tumor portion from the abnormal images. The performance of the proposed hybrid technique had been analyzed using various evaluation parameters. The simulation results revealed that the proposed method's statistical evaluation parameters are much better compared to the other traditional methods such as CNN, fuzzy-K-means, SS2DCN, and KNN. The main advantage of the proposed method was that it predicted not only the size of the tumor but also the type of tumor (benign or malignant). For future studies, we want to develop various hybrid techniques to classify and segment MR brain images.

CONFLICTS OF INTEREST

None.

ETHICAL APPROVAL

The manuscript does not contain studies with human participants or animals, and there is no funding organization for this research work.

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